Wireless 3D Point Cloud Delivery Using Deep Graph Neural Networks

Takuya Fujihashi¹, Toshiaki Koike-Akino², Siheng Chen^{2,} Takashi Watanabe¹, ¹Osaka University ²Mitsubishi Electric Research Laboratories (MERL)

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Background

Volumetric (3D) media

- Reconstruct 3D scenes with full parallax and depth info.
- Applications: entertainment, medical imaging, AR/MR



Key applications in 5G and 5G beyond networks [1]

- Google and Facebook investigate volumetric video streaming
- Volumetric video market will grow from \$578 million in 2018 to \$2.78 billion by 2023 [2]



[1] AT&T Continues to Lead in Bringing 5G Experiences to Life, 2018.
 [2] Volumetric Video Market by Volumetric Capture & Content Creation (Hardware (Camera & Processing Unit), Software, and Services), Application (Sports & Entertainment, Medical, Signage, Education & Training), and Geography - Global Forecast to 2023.

Point Cloud

- Typical data structure for 3D scene
 - Consist of numerous and irregular structure of 3D points
 - Each point has 3D coordinate (x, y, z) information





Issues of Digital-based Wireless Point Cloud Streaming



Issues of Digital-based Wireless Point Cloud Streaming



Purpose

- Our study tackles the following challenging issues
 - 1. Cliff effect
 - 2. Leveling effect: Constant reconstruction quality
- Propose a novel scheme for wireless point cloud delivery
 - Regard 3D points as graph signals with the attributes of 3D coordinates to deal with irregular structure of holographic data formats
 - Introduce graph neural network (GNN)-based and multi-layer perceptron (MLP)-based autoencoder for point coding
 - Skip digital-based compression, instead, introduce nearanalog modulation to realize graceful quality improvement

GNN

- Extend neural networks to process graph signals
 - Deal with signals in non-Euclidean space
- Applications
 - Physics, Molecule, Text, Social networks, Images
- Typical GNN model
 - Find graph structure
 - Design loss functions and computational modules



Proposed: Graph Construction



- Regard 3D points as graph $g = (V, \epsilon, W)$
 - V: vertex (each 3D point), ϵ : edge
 - W: adjacency matrix of positive edge weights
 - $W_{i,j}$: the weight of an edge connecting vertices *i* and *j*
 - I: vertices are connected, 0: vertices are not connected
 - Use K-nearest-neighbor graph to make the connection between the vertices

Proposed: GNN-based Encoder

Transforms 3D points into several latent variables

 Consists of a series of graph convolution followed by leaky rectified linear unit (ReLU) activation function, Top-K pooling, and a normalization layer



Proposed: GNN-based Encoder

- Graph Convolution: Extract the graph signal features
- Leaky ReLU: learn a mapping from the source to coded signals
- Top-K Pooling: chooses the largest values from each channel to remain important features





Near-analog modulation realizes graceful quality improvement according to wireless channel quality



Proposed: MLP-based Decoding

- Latent variables z_i are impaired according to a channel transfer function with pre/post equalizations
 - $\eta_{\text{preeq}} = |h_i|z_i + n_i$
 - $\eta_{\text{posteq}} = z_i + n_i / h_i$
 - *h_i*: multiplicative fading coefficient
 - n_i: effective noise
 with a variance of σ²

Decoder

 Consists of a series of fully-connected layers and leaky ReLU



Proposed: Loss Function

- GNN-based encoding and MLP-based decoding functions are trained to minimize a loss function
 - $(\theta, \phi) = \arg\min_{\theta, \phi} \mathbb{E}[d(\mathbf{p}, \widehat{\mathbf{p}}_{\theta, \phi})]$
 - $\hat{p}_{\theta,\phi}$: reconstructed 3D coordinates via the proposed encoder and decoder with parameter sets of θ and ϕ



$$\max\left\{\frac{1}{|S|}\sum_{p\in S}\min_{\widehat{p}\in\widehat{S}}\left|\left|p-\widehat{p}\right|\right|_{2},\frac{1}{|\widehat{S}|}\sum_{\widehat{p}\in\widehat{S}}\min_{p\in S}\left|\left|p-\widehat{p}\right|\right|_{2}\right\}$$

 If Chamfer distance is even small, the original and reconstructed 3D coordinates are close each other



Evaluation

- Comparative schemes
 - SoftCast [3]:
 DCT-based
 - HoloCast [4]:GFT-based





Reference point cloud

HoloCast

ShapeNet: dataset of 3D points

14 [3] S. Jakubczak and D. Katabi, "A cross-layer design for scalable mobile video," in ACM Annual International Conference on Mobile Computing and Networking, Sep. 2011, pp. 289–300. [4] T. Fujihashi, T. Koike-Akino, T. Watanabe, and P. Orlik, "HoloCast:Graph signal processing for graceful point cloud delivery," in IEEE International Conference on Communications, 2019, pp. 1–7

Evaluation

Reference point cloud

- ShapeNet: dataset of 3D points
 - Category: Airplane
 - 2115 point clouds for training,
 234 point clouds for testing



Reconstruction Quality vs. Wireless Channel Quality



Reconstruction Quality vs Traffic



Visual Quality of Point Cloud Reconstruction



HoloCast Chamfer distance: 0.003 Proposed Chamfer distance: 0.012



- Proposed a novel scheme for wireless point cloud delivery
 - Regard 3D points as graph signals with the attributes of 3D coordinates and color components to deal with irregular structure of holographic data formats
 - Introduce graph neural network (GNN)-based and multi-layer perceptron (MLP)-based autoencoder for point coding
 - Skip digital-based compression, instead, introduce nearanalog modulation to realize graceful quality improvement
- Validated the advantage

Conclusion

- Gracefully improve reconstruction quality with the improvement of wireless channel quality
- Better reconstruction quality with a limited amount of traffic

Q&A

Please send questions and comments fujihashi.takuya@ist.osaka-u.ac.jp